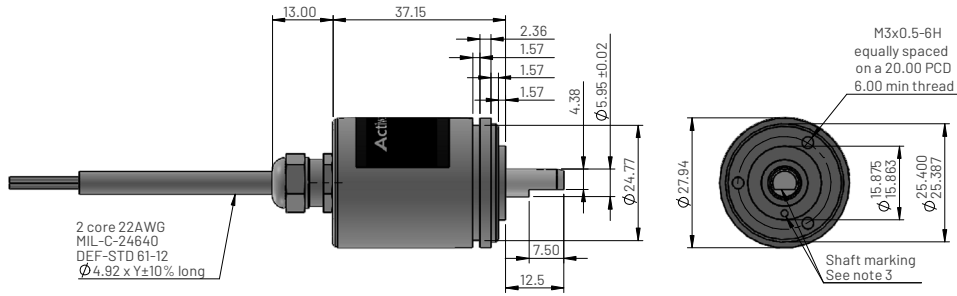


VRP1120 Current Output - Rotary potentiometer

High performance series

Dimensions for VRP1120 - Synchro mounting with rear cable exit



Ordering information

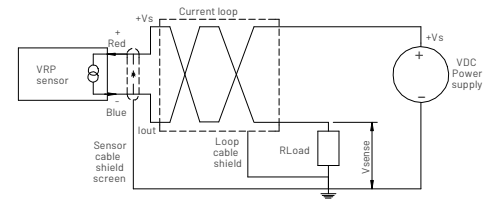
VRP1120-11-XXX-Y-AA1

Electrical angle in degrees
 Cable length 0 to 9
 0 - 0.5m, 1 - 1m ... 9 - 9m
 Output direction (viewed on shaft)
 A = anticlockwise
 Output signal
 A1 = 4-20mA

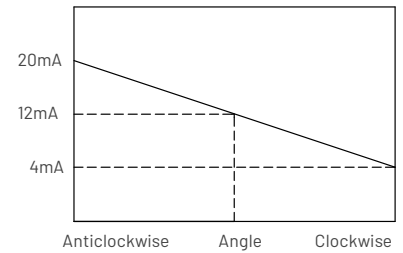
Electrical and mechanical specification

Parameters	Values	Units	Notes
Mechanical specification			
Electrical angle ($\pm 2^\circ$)	100, 130, 350	$^\circ$	
Mechanical travel	360 Continuous	$^\circ$	
Sensor weight (excluding cable)	60	grams	
Performance specification			
Non-linearity	$< \pm 0.50$	%FS	2
Resolution	Infinite		
Thermal drift	± 0.01 TBD	%FS/ $^\circ\text{C}$	
Electrical specification			
Input voltage (+Vs)	12 to 40	VDC	
Line regulation	< 0.002	%FS/V	7
Reverse polarity (+Vs)	-60	VDC	
Output current (Iout)	2 wire 4-20	mA	
Sensitivity $< \pm 2\%$	0.160, 0.120, 0.046	mA/ $^\circ$	2
Loop resistance (max)	$(+Vs - 8V) / 0.02A$	ohms	8
Output noise and ripple	< 0.05	%FS RMS	
Electrical connections	2 core x 22AWG (screened) Zerohal jacket		
Cable length (max)	0.5 to 9.0	m	9
Environmental specification			
Operating temperature range	-30 to +105	$^\circ\text{C}$	
Environmental	IP67		
Materials	Sensor	Case - Anodised aluminium alloy 6063-T5, Shaft - Stainless steel	
	Cable gland	Nickel plated brass	

Electrical connections (see note 1)



VRP mA output schematic



Notes

1. Incorrect wiring may cause internal damage.
2. Non-linearity error and sensitivity is calculated from least squares best fit method.
3. When shaft flat is facing case shaft mark the instrument is mid-travel.
4. Average thermal drift over operating temperature range.
5. Nominal bandwidth (-3dB) with a 1st order (-20dB/decade) roll-off.
6. Within 20 seconds of power on condition and over 30 minutes period. (Whilst delta temperature sensor $< 2^\circ\text{C}$)
7. When +Vs = +12VDC to +30VDC.
8. Includes all wiring resistance and RLoad resistance.
9. Includes all wiring between sensor and RLoad.
10. General dimension tolerance is ± 0.25 .